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Understanding stroke survivors' preferences regarding wearable sensor feedback on functional movement: a mixed-methods study

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Abstract

Background In stroke rehabilitation, wearable technology can be used as an intervention modality by providing timely, meaningful feedback on motor performance. Stroke survivors' preferences may offer a unique perspective on what metrics are intuitive, actionable, and meaningful to change behavior. However, few studies have identified feedback preferences from stroke survivors. This project aims to determine the ease of understanding and movement encouragement of feedback based on wearable sensor data (both arm/hand use and mobility) for stroke survivors and to identify preferences for feedback metrics (mode, content, frequency, and timing).

Methods A sample of 30 chronic stroke survivors wore a multi-sensor system in the natural environment over a 1-week monitoring period. The sensor system captured time in active movement of each arm, arm use ratio, step counts and stance time symmetry. Using the data from the monitoring period, participants were presented with a movement report with visual displays of feedback about arm/hand use, step counts and gait symmetry. A survey and qualitative interview were used to assess ease of understanding, actionability and components of feedback that users found most meaningful to drive lasting behavior change.

Results Arm/hand use and mobility sensor-derived feedback metrics were easy to understand and actionable. The preferred metric to encourage arm/hand use was the hourly arm use bar plot, and similarly the preferred metric to encourage mobility was the hourly steps bar plot, which were each ranked as top choice by 40% of participants. Participants perceived that quantitative (i.e., step counts) and qualitative (i.e., stance time symmetry) mobility metrics provided complementary information. Three main themes emerged from the qualitative analysis: (1) Motivation for behavior change, (2) Real-time feedback based on individual goals, and (3) Value of experienced clinicians for prescription and accountability. Participants stressed the importance of having feedback tailored to their own personalized goals and receiving guidance from clinicians on strategies to progress and increase functional movement behavior in the unsupervised home and community setting.

Conclusion The resulting technology has the potential to integrate engineering and personalized rehabilitation to maximize participation in meaningful life activities outside clinical settings in a less structured environment.

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Keywords Wearable electronic devices, Stroke, Rehabilitation, Feedback, Mobility, Upper extremity, Behavior change

Background

The aging of the population in the United States have led to an increasing need for solutions to promote rehabilitation outside clinical settings [1]. Increasingly, wearable sensors have been recognized as a potential response to this growing need [2, 3], due to their capacity to capture functional movement behavior (both locomotion and arm and hand use) and provide timely, meaningful feedback to the user about motor performance. Understanding how stroke survivors perform in the home and community, within its unstructured and often unpredictable context, can be useful to guide personalized clinical interventions [4]. Wearable technology can be used as both a contextually relevant assessment method and simultaneously an intervention modality to facilitate behavior change through provision of direct feedback to the user about their activity [5, 6]. Mobile applications can often be combined with wearable sensors to offer reminders, encouragement, education, or messages to indicate how many more steps/minutes of activity are needed to achieve personal activity goals. The benefit of wearable technology (i.e., digital therapeutic) for stroke rehabilitation include their unobtrusive nature (i.e., data can be captured without hindering everyday activities) and most importantly the possibility to deliver therapy in the context of an individuals' everyday life [7, 8].

Feedback based on wearable sensor data can encourage health-promoting behaviors for stroke survivors, such as physical activity and the choice to engage functional behaviors (e.g., upper limb use, mobility activities) [2]. For stroke survivors, strong evidence supports the provision of extrinsic feedback to elicit motor learning processes and improve motor recovery [9]. There is growing evidence that extrinsic feedback can positively influence motivation, self-efficacy, and compliance [10, 11]. Feedback based on wearable sensor data may include objective measures of activity (e.g., step or movement count, sedentary time, time in active movement for each arm), graphs of daily activity, or reminders/encouragement towards activity goals (e.g., encouragement to close your activity ring) [2, 12]. Feedback frequency and timing (e.g., daily, weekly, on-demand, when someone is inactive for a prolonged period), mode (e.g., auditory, haptic, or visual), and content can vary from one system to another. However, while these attractive features of a wearable sensing system are all possible, it does not follow that they are all inevitable! On the contrary, a wearable sensing system must be carefully designed to foster these desirable

features and attributes. Moreover, due to the many options of feedback metrics (mode, content, frequency, and timing), it can be challenging to make informed design decisions on what may be best to drive behavior change for an individual stroke survivor with their unique demographic, psychosocial and clinical profile.

To date, few studies have identified feedback preferences from stroke survivors. In a stakeholder survey of a wearable activity monitor for upper limb recovery, 35% of stroke survivors preferred feedback via a combination of vibration and sound whereas 29% preferred a visual message [13]. In a systematic review on wearable sensors for upper limb rehabilitation across different health conditions, visual display was the most common way to provide feedback. Most systems attempt (either intentionally or intuitively) to indicate progress towards an understood skill or goal, an approach known in the field of psychology as Knowledge of Results [12]. To promote skilled motor recovery and maximize community participation, wearable sensors need to *provide actionable feedback* about movement quantity and quality that users can understand and implement to motivate activity and change behavior. Here, actionable feedback is defined as a movement performance metric that can be acted upon by stroke survivors in a way that increases the frequency of desired behavioral patterns in their daily life [14]. If the ultimate goal is to personalize the digital therapeutic, it is equally important to understand the feedback preferences from the user; in this case, community-dwelling stroke survivors.

This work is part of a larger project aiming to test the feasibility of the wearable technology, and to develop a data-driven and clinically informed behavioral intervention strategy for a wearable sensor system that uses actionable feedback to maximize physical function after stroke [15, 16]. As an initial probe into the use of a wearable sensor system that can capture both upper and lower limb functional behavior in the community, we decided to provide terminal feedback to learn about preferences. By design, we chose not to provide concurrent feedback during the observation period, in part, to control for the likely possibility that the feedback would change stroke survivors' behavior. Thus, we identified various terminal feedback metrics that are intuitive and relevant clinically from our in-lab validity and usability testing [15, 16], the literature [12], our scoping review that included an online consultation survey exercise with 37 experts [3] and the team's clinical experience in stroke rehabilitation and motor learning.

This project aims to: (1) determine the ease of understanding and movement encouragement of feedback based on wearable sensor data (both arm/hand use and mobility) for chronic stroke survivors, (2) identify stroke survivors' preferences for feedback metrics (i.e., mode, content, frequency, and timing) that has the potential to drive health-supporting behavior change. We hypothesized that the 'Arm Use Ratio' and the 'Hourly Step Counts' would be the preferred metrics, as both measures are simple and intuitive.

Methods

Study design

This study used a mixed-methods convergent design [17] to identify feedback preferences of stroke survivors. This design consists of collecting and analyzing quantitative and qualitative data separately, then merging those data for the omnibus discussion where an interpretation is presented. We used a quantitative survey to identify ease of understanding and actionability of each feedback metric, whereas qualitative semi-structured interviews allowed a deeper understanding of users' feedback preferences needed to drive lasting behavior changes. The collection of qualitative and quantitative data allowed a rich, comprehensive, and actionable dataset to inform future development of a user-centered digital therapeutic intervention.

Participants

Community-dwelling stroke survivors aged >18 years old, independent with home or community ambulation (with or without supervision) and fluent in English were included. We excluded participants with unilateral spatial neglect, severe cognitive or language impairments or other medical condition that may interfere with participation. Communication facilitation strategies were used to allow participants with mild-moderate aphasia to participate. The sample size was based on the concept of data saturation for the semi-structured interview data. It was estimated that a sample of 25–30 stroke survivors would be sufficient to reach saturation. Stroke survivors were recruited from the IRB-approved Registry for Healthy Aging Database (RARE). We also recruited a convenience sample of ten age-matched non-disabled neurotypical participants through contacts of the research team and email advertisement. Neurotypical participants were recruited, and their data was presented to the stroke survivor cohort so they would be able to compare and interpret their performance relative to a non-disabled peer. All participants were fully informed of the procedures involved and provided informed consent. Study procedures were approved by the Institutional Review Board at

the University of Southern California (HS 19-00984 and HS 20-00015).

A total of 30 chronic stroke survivors (mean 7.6 years post-stroke) took part in this study (see Table 1 for participant characteristics). The mean and standard deviation age was 58.6 ± 13.1 years. Participants had mild stroke severity on the National Institute of Health Stroke Scale (mean: 2.8 ± 2.0) [18] and mild-severe motor impairments (Fugl-Meyer Assessment score: mean: 41.2/66). Most participants were independent in ambulation (60% with a Functional Ambulation Scale of 5) and the average self-paced gait speed was 0.75 ± 0.40 m/s.

Procedures

Stroke survivors wore a wearable sensor system (MiGo, Flint Rehabilitation Devices, Irvine, CA) for a 1-week, whereas neurotypical participants wore the system for 24 h. The MiGo system consists of two wristwatches and a sensor strapped around each ankle. While the MiGo has feedback capability, feedback from the wristwatch was intentionally disabled during the monitoring period, as it had the potential to change behavior. We acknowledge that this is somewhat artificial, but it was done in line with this being an initial probe into the use of these sensors remotely, embedded in the everyday life of 30 stroke survivors. To facilitate donning/doffing, the wristband on the less affected side was replaced by an elastic strap. Prior to the monitoring period, the research team collected demographic and clinical data and provided information on how to don/doff and charge the sensors. Participants were instructed to wear the sensors for 12 h/day and continue their typical activities.

Each MiGo sensor contained a six degree-of-freedom inertial measurement unit (IMU) measuring acceleration and orientation. In stroke survivors with a wide range of motor impairments, the accuracy of the MiGo ranged from 85 to 88% to track time in active movements for each arm, 96% for step count and 90% for stance time symmetry [16]. The price of each sensor was approximately \$200 USD. The system could be loaned to stroke survivors followed in rehabilitation by the institution or purchased by stroke survivors after the end of their rehabilitation.

Participants were given a cellular gateway (Tenovi Health, Irvine, CA) that automatically retrieved logs from the MiGo devices every 3 h and conveyed them to a secure, HIPAA compliant server accessible only to members of the research team.

After the monitoring period, participants returned the equipment and met with a member of the research team in-person or remotely using the Zoom Meetings platform (Zoom Video Communications, San Jose, CA). Before the meetings, the team used a custom-built client application

Table 1 Participant characteristics

Characteristic	Mean \pm SD or n
Gender (%)	Men: 18 Women: 11 Non-binary: 1
Age (years)	58.6 \pm 13.1
Race (%)	American Indian or Alaska Native: 0 Asian: 5 Black: 5 Native Hawaiian or Pacific Islander: 3 White or Caucasian: 11 More than one Race: 5 Not reported/unknown: 1
Ethnicity (%)	Hispanic: 10 Non-Hispanic: 21
Time since stroke (years)	7.6 \pm 4.5 (range: 1.0–21.2)
Hemisphere affected by the stroke (%)	Left: 18 Right: 12
Stroke classification (%)	Hemorrhagic: 7 Ischemic: 21 Not reported: 2
Limb concordance (%)	18
National Institutes of Health Stroke Scale (/42)	2.8 \pm 2.0
Montreal Cognitive Assessment (/30)	24.7 \pm 3.4
Fugl-Meyer Assessment Upper Extremity (/66)	41.2 \pm 18.0 (Range: 18–66)
Functional Ambulation Category (%)	3:4 4:8 5:18
10-Meter Walk Test (m/s)	Self-paced: 0.75 \pm 0.40 Fast paced: 0.96 \pm 0.53

to request data from the server and process it to generate individualized movement reports. (Fig. 1 and Table 2).

In the follow-up visit, participants were oriented to each graph on the movement report on a computer and reviewed the report with a research therapist. A 24-h movement report from an age- and gender-matched neurotypical participant was also presented as a comparison to assist participants in the interpretation of their individualized report and to begin a discussion about their goals. Once the participant understood the movement report, they were asked to complete the movement report survey. We then conducted a 30-min semi-structured interview about feedback preferences (mode, content, frequency, and timing) with each participant.

Data acquisition from wearable sensors: Movement detection was based on the accelerometer data from three axes (x, y, z). We used a built-in algorithm on the wristwatch to automatically band-pass filter the raw accelerometry data, remove the effect of gravity, and convert acceleration into time in active movement for the upper limb and step counts. For stance time, the sensor quaternion was used to detect heel stroke events. Stance time was estimated by measuring the time spent in stance phase of the gait cycle for both lower limbs. During the

monitoring period, the watches logged upper limb active time and the ankle sensors logged both step counts, and the average percent of the gait cycle spent in the stance phase. Logs were saved every quarter hour. For upper limb active time and step count, logs recorded the current daily total. For stance percent, the estimate was reset every 15 min and a new estimate was collected in every log period.

Feedback based on wearable sensor data: By design, we decided to offer terminal feedback in the form of a visual display at the end of the monitoring period for two reasons: (1) to avoid modifying stroke survivors' behavior during the monitoring period by providing real-time feedback, (2) mimic how clinicians would discuss outcomes captured with wearable technology with their clients and set individualized goals. We selected metrics that were simple to understand, intuitive and frequently used in the literature [12, 13, 23, 24]. Data from the left and right sensors were color coded as blue and orange respectively and whenever possible data from the left and right sensors were shown on corresponding sides of the plots. Because the plots were intended for interpretation by the end users, more complicated features like error bars that might normally increase depth of interpretation

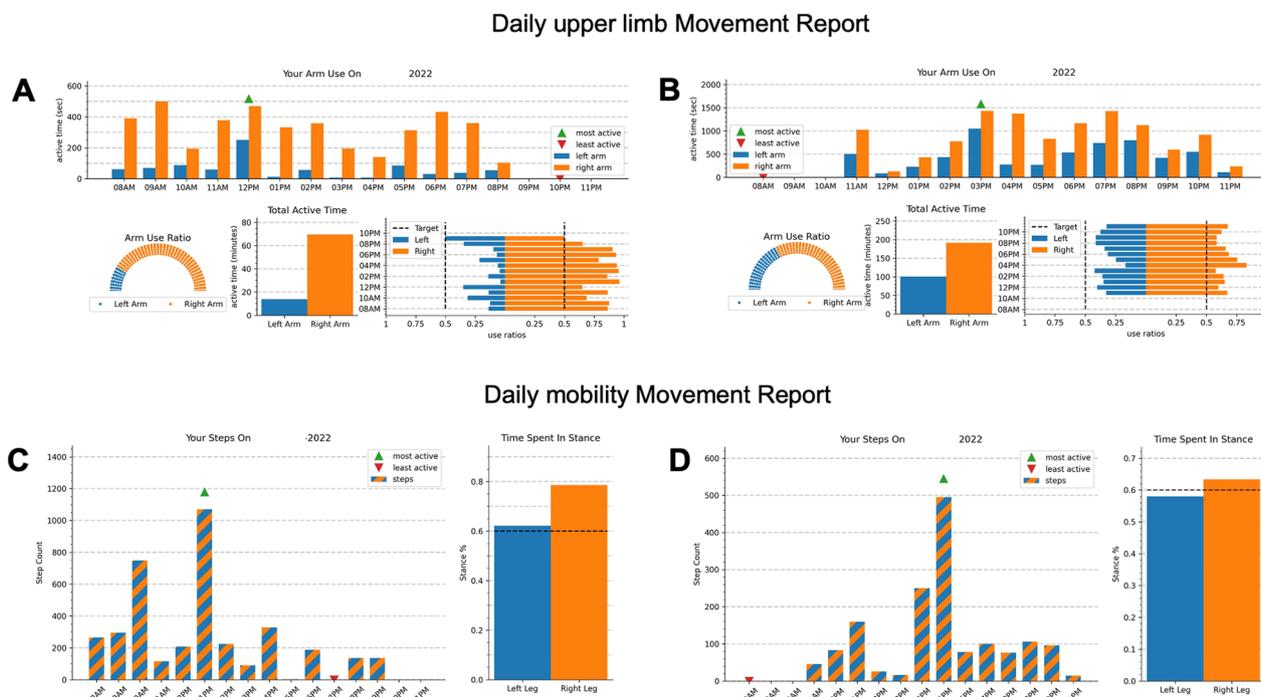


Fig. 1 Example of daily movement reports: Example of two daily movement reports generated after a 1-week monitoring period for two representative participants with a right hemispheric stroke: one with severe motor impairments (**A** and **C**; Fugl-Meyer Assessment score of 28/66, Functional Ambulation Category of 3—supervision) and one with mild motor impairments (**B** and **D**; Fugl-Meyer Assessment score of 64/66, Functional Ambulation Category of 5—-independent). Left (paretic) arm/leg movements are in blue (dark), and Right (less paretic) arm/leg movements are in orange (light). **A** and **B** The top graphs represent the daily upper limb, movement report with an hourly arm use bar graph (top), a dial plot (bottom left), a daily active time bar graph (bottom center) and an arm use ratio horizontal bar plot (bottom right). **C** and **D** The bottom graphs represent the daily mobility movement report with the hourly step counts on the left and the time spent in stance on the right

were omitted in favor of simplicity. For each participant, a daily and a weekly report were generated. For each report, we decided to limit the number of metrics to four, again in favor of simplicity. The upper limb daily report consisted of four upper limb metrics: Hourly arm use bar graph, Arm use ratio dial plot, Total active time bar plot and Use ratios (horizontal bar plot). The upper limb weekly report consisted of the same graphs, with the data averaged over a week. The daily mobility report consisted of the Hourly steps bar plot and the Time spent in stance, whereas the weekly report consisted of the Daily steps bar plot and the Stance % this week.

To estimate active time for the at-home portion of our experiment, we used a threshold filter. We computed the acceleration magnitude, removed the static 1 g offset from gravity, and applied a low pass filter (second order Butterworth with a cut-off of 3.8 Hz). For each sample, if the filtered magnitude was above a given threshold (0.03 g), we incremented the active time by the delta time for that sample. This adheres closely to a standard approach used by most accelerometry studies [25–27]. Our specific filter parameters and threshold were determined by using particle swarm optimization to find

values that minimized error in a training set of activities of daily living between the algorithm and active time measured by trained therapists annotating synchronized video data [16].

All upper limb metrics were generated from the available active time logs for a given participant on a given day. The difference from one log to the next was taken to determine the amount of active time in each 15-min bin. For each bin, we computed the ratios of the left and right arm active times to the total combined active time to obtain the normalized use ratio. For each day in the dataset, we resampled the data into 1-h bins and generated a report showing the hourly active time, the total active time for the day, the normalized active time ratio for the day, and the hourly active time ratio. We resampled the data into one-day bins and generated a report for the entire week showing the total active time for each day, the average normalized use ratio for the week.

To detect heel strike events at the ankle, we used the sensor quaternion to obtain the pitch angle of the ankle in the global reference frame. To correct for postural differences and small differences in sensor placement, we used a high pass (second order Butterworth) filter with

Table 2 Detailed description of each metric in the movement report

Metric	Description	Rationale for selection
Upper limb metrics		
Hourly arm use bar graph	This vertical bar plot indicated the total active time of each arm at each hour (from 8am to 11 pm). A green and a red arrow indicates the hour with the most or the least activity	To illustrate arm use activity throughout the day [12]
Arm use ratio dial plot	This dial plot displayed the percentage of time in active movement between the right and left arms/hands on a half-circle	To quickly see the symmetry of arm/hand movements [12, 19]
Total active time bar plot	This vertical bar plot indicated the total active time of each arm over the entire day	To provide an overall measure of the activity of each arm/hand [12, 19]
Use ratios (horizontal bar plot)	This horizontal bar plot displayed the average arm use ratio for each hour. The vertical dotted lines indicated a potential target for symmetrical use of both arms	To visualize movement symmetry throughout the day We anticipated that this plot may be harder to understand for stroke survivor [12]
Mobility metrics		
Hourly steps bar plot	This vertical bar plot displayed the total number of steps taken by this participant every hour from 8am to 11 pm. A green and a red arrow indicates the hour with the most or the least steps	To show the frequency at which the steps are accrued throughout the day [2, 20]
Time spent in stance	This vertical plot displayed the time spent in stance on the right and left legs, averaged over the day	To offer gait quality metric This may be relevant for clinicians and potentially, stroke survivors [21]
Daily steps bar plot	This vertical bar plot displayed the total number of steps for each day of the week. A green and a red arrow indicates the day with the most or the least steps	To show the walking volume and offer insights as to whether this outcome is consistent or variable between days [2, 22]
Stance % this week	This vertical plot displayed the time spent in stance on the right and left legs, averaged over the day	To offer gait quality metric and offer insights as to whether this outcome is consistent or variable between days [21]

a cut-off of 0.1 Hz to remove the offsets from the ankle pitch measurements. Pitch was defined as positive when the leg was in an extended position and negative when it was in a flexed position. We then used peak detection algorithms to detect the peak and trough events in the pitch data. Heel strike events occurred when the ankle was at its maximum pitch angle, and toe-off events occurred just after pitch angle trough events. To estimate stance time, we measured the time between consecutive peaks and troughs.

Similar to the upper limb metrics, the client application generated reports for mobility. For each day, the daily movement report showed the hourly step count and the average stance percent estimates for both legs. The weekly report showed the daily step counts and the stance percent estimates for each day. Stance percent estimates from logs containing less than 25 steps in a 15-min period were excluded from the reports.

Quantitative: Participants completed the Montreal Cognitive Assessment [28] and the National Institutes of Health Stroke Scale [18], as descriptive measures of cognitive function and stroke severity, respectively. Arm and hand motor impairments were characterized using the Fugl-Meyer Assessment upper extremity (severe: 0–28, moderate: 29–42, mild: 43–66) [29]. Walking ability was

categorized using the Functional Ambulation Category (3: walk with supervision; 4: walk independently on ground level; 5: walk independently anywhere) [30] and the 10-m walk test [31].

Stroke survivors answered a movement report survey, which consisted of 19 visual analogue scales on a 10-cm line representing their ranking. They graded their responses based on ease of understanding (from very difficult to very easy) and movement encouragement (strongly disagree to strongly agree) for all arm/hand and mobility metrics. We used the term ‘movement encouragement’ as a proxy for actionability, to facilitate comprehensibility for stroke survivors with lower education levels, cognitive or language impairments. However, we acknowledge that the term ‘movement encouragement’ is not as comprehensive as the term ‘actionability’. Higher scores indicated greater ease of understanding or movement encouragement. Participants were also asked to rank what they would prefer to see in the future by numbering each metric from 1 (highest) to 4 (lowest). Scores were derived from the visual analogue scales by measuring with a ruler the distance in millimeters between the participant’s mark and the 0.

Qualitative: Semi-structured interviews were conducted in a closed room and were audio-recorded to

facilitate verbatim transcription. Interview questions were based on an interview guide and structured to identify feedback preferences, usefulness of the movement report, and how feedback would be used in daily activities (see the Interview Guide in the Supplementary file). The main ideas expressed during the interview were summarized at the end of each interview for member checking (i.e., the process of soliciting feedback from a participant about their data and interpretations [32]).

Data analysis

Quantitative Descriptive statistics were used to characterize our sample. We compared the mean ‘ease of understanding’ and ‘movement encouragement’ score of each feedback metric to identify any differences, using Friedman’s tests. When the Friedman test yielded a significant main effect, we performed post-hoc pairwise comparisons using the Wilcoxon signed-rank tests and p-values are adjusted using the Bonferroni multiple testing correction method. All statistical analyses were performed in JASP version 0.16.4, with a significance level set at $p < 0.05$.

Qualitative Interviews were transcribed verbatim. Two independent researchers (MD and AC) used inductive thematic content analysis to interpret meaning from the context of textual data [33]. The Braun & Clark framework [34] was followed and a detailed code book listing all the codes and definitions was developed to facilitate thematic content analysis. The initial coding was initiated after the first five participants were collected and performed until data saturation was reached. Data saturation

was determined when no new codes emerged, and the ideas were repeated among participants. Repeated discussions occurred between the two coders to clarify interpretation of the data. A third reviewer (CJW) participated in the discussion related to refining the themes and data interpretation. Qualitative data analysis was performed using the NVivo software (QSR International Pty Ltd, Melbourne, Australia). Any disagreement was resolved by discussion and an audit trail was kept for the rationale behind every decision.

Integration of qualitative and quantitative data Quantitative and qualitative data about feedback preferences were integrated once data analysis was completed to identify metrics that are intuitive, actionable, and meaningful to drive positive behavior change.

Results

Quantitative

Overall, the arm/hand and mobility metrics were easy to understand and encouraged movements (see Fig. 2 for the average scores). For the arm/hand metrics, there was a difference between the ratings of the four metrics for the ‘ease of understanding’ ($\chi^2(3) = 10.500$; $p = 0.015$), but not for ‘movement encouragement’ ($\chi^2(3) = 4.324$; $p = 0.229$). Pairwise Wilcoxon signed rank test revealed statistically significant differences in the ‘ease of understanding’ scores of Use ratios 2D histograms and the Hourly arm use bar plot ($Z = 3.169$; $p = 0.013$); and the Use ratios 2D histograms and Total active time bar plot ($Z = 3.104$; $p = 0.015$). The Friedman’s test revealed no difference between mobility metrics (‘ease of

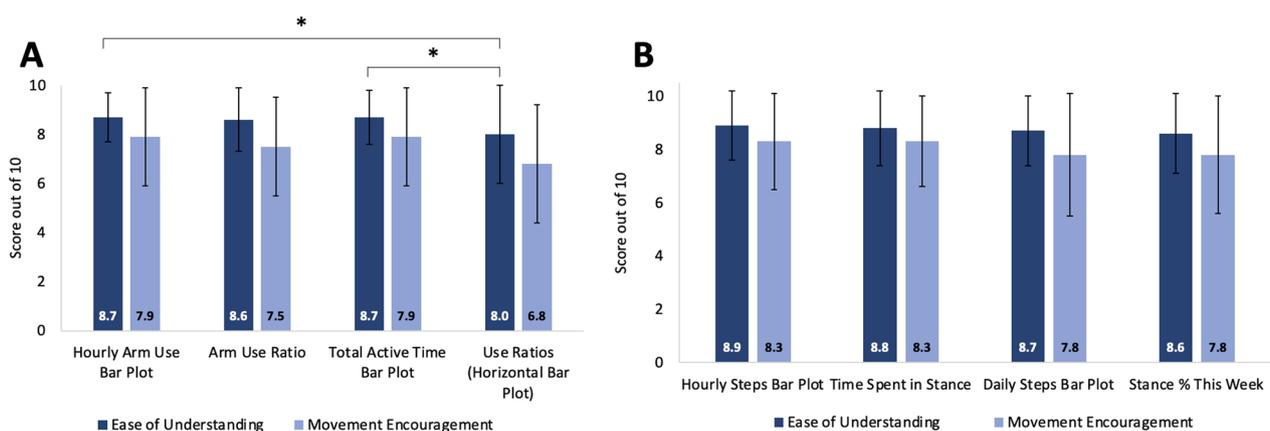


Fig. 2 Rating of ease of understanding and movement encouragement of each feedback metric: The average scores were rated out of 10 for ease of understanding and movement encouragement from the visual analogue scales on the movement report survey. Ease of understanding scores are in dark blue, and movement encouragement scores are in light blue for each (A) arm/hand and (B) mobility metric. The * denotes a pairwise significant difference between the Hourly arm use bar plot and the use ratios, and the Total active time bar plot and the Use ratios for the ‘Ease of understanding’ scores

understanding’: $Z=3.900$; $p=0.272$; ‘movement encouragement’: $Z=3.327$; $p=0.344$). When participants were asked to rank preferences for arm/hand ‘movement encouragement’, the Hourly arm use bar plot (Fig. 1A and B) was ranked the highest by 40.0% of participants followed by the Daily arm use bar plot (Fig. 1A and B; 26.7%) and the Arm use ratio (Fig. 1A and B; 23.3%). For Mobility, Hourly steps bar plot (Fig. 1C and D) was preferred by 40.0% of participants, followed by Daily steps bar plot (36.7%) and Stance % this week (13.3%; see Fig. 3 for ranking preferences). These results reject our hypothesis that the ‘Arm use ratio’ and the ‘Hourly step counts’ would be the preferred metrics, as no clear preferences were obtained.

Qualitative

Three main themes emerged from the qualitative data analysis: (1) Motivation for behavior change, (2) Need for real-time feedback based on individual goals and (3) Value of guidance from experienced clinicians for prescription and accountability. In the next section, each emergent theme is summarized along with exemplar quotes from each individual participants (i.e., S#).

Theme 1: Motivation for behavior change: This theme encompassed the perceived benefits of the wearable technology to encourage healthier movement behavior. The

wearable technology was perceived as motivating and as a complement to rehabilitation care. Participants reported that the feedback metrics were easy to understand after they were oriented to each metric, with mobility metrics being easier to understand than the arm/hand metrics.

S44: ‘The report is very clear and easy to understand.’
S17: ‘[The mobility graphs] were more understanding [sic] than the arm graphs.’

While the feedback capability was deactivated during the data collection period, motivation for behavior change and the prospect to track one’s progress was identified as a potential benefit of the wearable technology. Participants were encouraged to see their motor performance on the movement report. For some, it validated their own performance assessment, while others were surprised about their daily performance and indicated that it was encouraging.

S03: ‘Knowing how much movement you do during the day and the week is very helpful and kind of gets you to want to do a little bit more. [The sensors] are a tool to find out how you’re doing. That’s motivation.’
S12: ‘I liked the graphs. They were very encouraging because I didn’t know I was moving that much.’

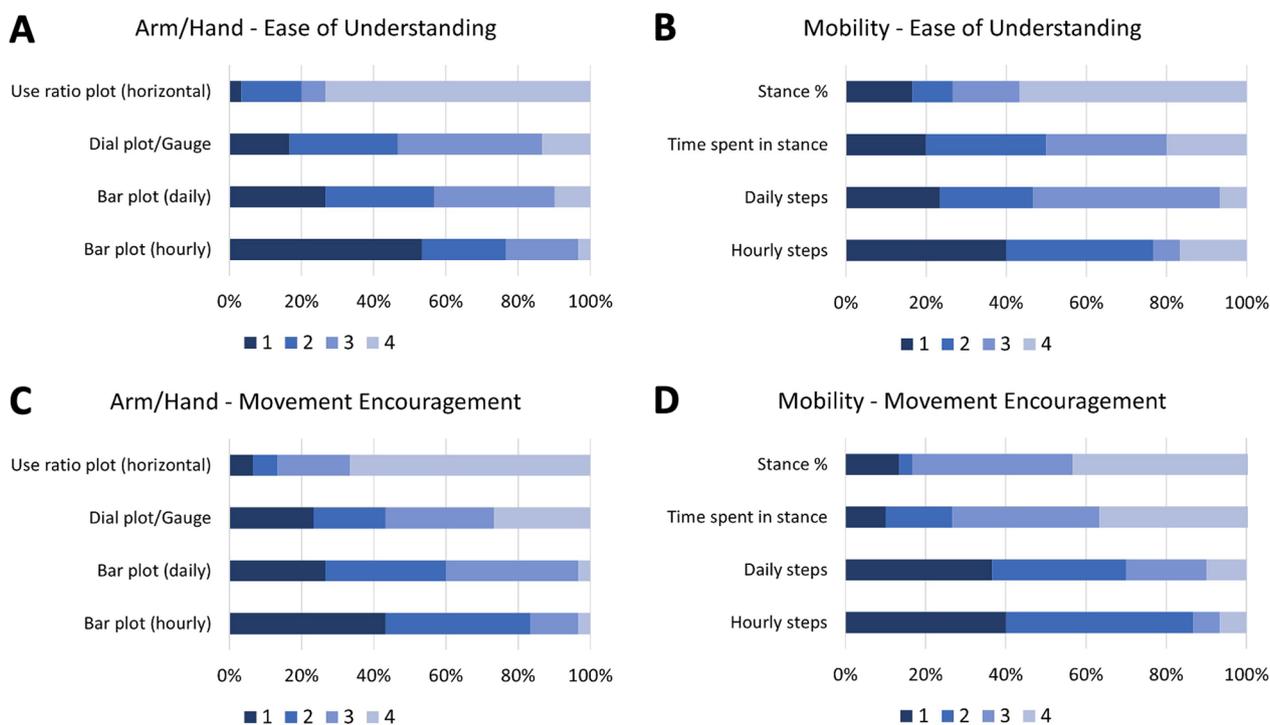


Fig. 3 Ranking preferences for each feedback metric: Ranking preferences (1 is the most preferred and 4 is the least preferred) for ease of understanding (A and B) and movement encouragement (C and D) for arm/hand (A and C) and mobility (B and D) metrics

S09: 'I didn't even know [my paretic arm] was moving that much. I'm very happy.'

Participants with severe motor impairments perceived that they were already using their paretic upper limb at their maximum capacity. They indicated that receiving feedback would have limited usefulness, as they did not have enough function of their paretic limb to use it more. They did not intuit a way that they could act on the provided feedback. Improving capacity or problem-solving with participants on how the more affected arm can be incorporated in daily activities may be more useful for participants with severe motor impairments.

S18: 'I don't think any report about using my arm would do anything, because I use my arm as much as I can.'

Theme 2—Real-time feedback based on individual goals: The lack of real-time feedback delivery was identified by many participants as a limitation of our study design, as participants preferred to get something out of the wearable technology. Participants discussed the relevance to receive personalized feedback when needed (i.e., self-controlled feedback). For some participants, a daily summary sent by email was judged sufficient, while most preferred to receive feedback in real-time, directly on the watch or a companion application.

S22: 'I liked what I saw. I would just want it sooner, so at the end of the day, you could see: "Oh, I haven't moved".'

S37: 'An app would be really good, because I usually always have my phone with me. I could kind of look and say 'Oh, you didn't move too much today. Maybe, you need to move a little bit more.'

Participants valued personalized goals. Most expressed wanting to receive feedback related to the accomplishment of their own goals and embed new goals as they progress.

S06: 'For me, it would be more like, convincing me more. Like you're giving me a certain [number] of steps that I will do. It challenges me.'

S05: 'I set myself goals that I do 12,000 steps a day, and I have to reach that goal.'

Theme 3—Value of experienced clinicians for prescription and accountability: Despite the potential of wearable technology to provide useful feedback directly to its users, participants reported that they would value meeting with experienced clinicians to help them set goals, to guide their progression and to help them problem solve ways to improve their upper extremity use habits. Many stroke survivors also reported that having goals and

frequent meetings with therapists to monitor behavior was ideal to promote behavior change, foster accountability and offer strategies to facilitate movement during daily activities.

S12: '[Wearable technology] would be huge along with what I received in therapy. This would be huge. That would be a powerful tool in rehabilitation.'

S17: 'I have to ask [therapists] questions. It'd be nice if I can meet with somebody.'

S31: 'The therapist would actually see how you're walking and stuff and give you tips.'

Quantitative and qualitative

While stroke survivors valued feedback on motor performance (i.e., time in active movement, arm use ratio, step counts or stance time symmetry), a single metric was not consistently identified in the surveys or interviews as being best for movement encouragement. For mobility, both quantitative and qualitative metrics were seen as useful and provided complementary information about gait. Visual feedback was appreciated by participants and a few reported that it could be enhanced by providing haptic or auditory feedback when a goal was met or to remind the participant to move. However, there was no consensus on whether people preferred positive (e.g., you're doing great!) or negative (e.g., you haven't moved in a while) feedback.

Discussion

This study aimed to identify stroke survivors' preferences for feedback metrics. Multiple sensor-derived metrics were identified as easy to understand and encouraging both arm/hand movements and mobility. Participants perceived that real-time feedback and daily summaries may be useful to induce behavior change. Stroke survivors stressed the importance to provide feedback in the context of individual goals to motivate engagement. Meeting with experienced clinicians in conjunction with wearable technology was valued to foster accountability and offer strategies to facilitate movement during daily activities. Sensor-derived feedback from wearable technology is a new area of research just as the use of wearable sensors are an evolving area of translational research. The novelty of this work is the use of both qualitative and quantitative methods with a diverse sample of stroke survivors to inform graphical terminal feedback design of wearable technology.

Individual preferences are important to consider in the design of an intervention [35]. Our results demonstrate that many different visual plots may be intuitive and encourage movement. Since data from wearable technology can be used by both stroke survivors and clinicians,

the balance between ease of understanding for stroke survivors and the amount of information to guide individualized treatment is delicate. A companion application for stroke survivors and clinicians could be a viable solution to allow users to access their preferred visual plot with advanced options for clinicians. Applications offer many possibilities to encourage health-promoting behavior. Application features and characteristics may include activity data visualization, self-monitoring, personalized goal setting, general or tailored education, reminders, and social support via social media or a community forum [36]. Simple metrics such as percentage of paretic arm use, step counts or stance time symmetry, identified as being actionable to stroke survivors, could be displayed directly on an activity watch and accessed when needed. Qualitative methods with experienced clinicians could be a future research direction to explore to complement our findings.

Consistent with the findings from Wang et al. [12], visual displays were valuable and could be combined with auditory or haptic feedback to draw attention to specific behavior (i.e., long periods of inactivity or goal achievement). Self-controlled feedback (i.e., ability to access information when desired) [37] was preferred by our participants. In the motor learning literature, evidence supports the use of self-controlled feedback to enhance motor learning [11]. Self-controlled feedback may encourage intrinsic motivation, support for autonomy and competence, as the individual takes charge of their own learning [11, 38, 39]. Our results also highlight the need to offer feedback in the context of individual goals. Goal setting is an integral part of stroke rehabilitation [40, 41]. Specifically, individualized goal setting may enhance motivation, adherence and autonomy, positively influence stroke survivors' perceptions of participation, and improve recovery and performance [42]. Consistent with the growing efforts for precision medicine in healthcare [43–46], personalized approaches to stroke recovery are needed to account for the heterogeneity of impairments and disability after stroke.

While wearable technology enables stroke survivors to track their progress, feedback alone was not sufficient to drive behavior change. Interventions should be carefully designed due to the complexity of behavior change. Simple feedback based on wearable sensor data alone (e.g., step counts) is not sufficient to change physical activity behavior of community-dwelling stroke survivors [47–49]. This emphasizes the importance to develop interventions using wearable technology that are grounded in strong theoretical foundations. Wearable technology should be integrated in clinical care to augment, not replace clinicians. Clinicians play a crucial role to offer personalized education. They also work collaboratively

with stroke survivors to identify strategies to encourage movement performance and prescribe exercises. Patient-therapist interaction and therapeutic alliance were shown to increase treatment adherence and satisfaction, and is directly linked to positive rehabilitation outcomes [50].

Finally, more work is needed to identify the characteristics of stroke survivors most likely to benefit from interventions using wearable technology. For stroke survivors with severe arm motor impairments, feedback may need to better adjust to suit their specific needs in a manner that is actionable to them. Previous work indicates that there might be a minimal threshold in motor capacity for stroke survivors to incorporate their paretic arm in daily activities [51–53]. For example, Chen et al. [53] demonstrated that a score of approximately 50 on the Fugl-Meyer Assessment upper extremity may be a significant cut-off point for engaging unimanual paretic movements in the unsupervised home environment. The predominant upper limb spontaneous movements that are seen in patients with Fugl-Meyer scores lower than 50 involve bimanual tasks for which the paretic limb acts as an assist to the less-impaired side [53]. If this threshold can be replicated in a larger sample, it may suggest that feedback be used to encourage bimanual movements for those below a score of 50 on the Fugl-Meyer motor assessment and unimanual paretic movements for those above a score of 50 on the Fugl-Meyer.

Limitations

A limitation to this study is that the participants were recruited from a database of survivors of stroke who volunteered to participate in research, limiting the generalizability of the results to the general stroke populations. These individuals may be more motivated to use the MiGo sensors and may respond more favorably to them. Therefore, we cannot exclude the possibility of a social desirability bias. By design, we did not assess the perceptions of stroke survivors for concurrent haptic or auditory feedback. These feedback modes will be seriously considered for our future intervention study. We also noticed a discrepancy between the visual analogue scale and the ranking (i.e., some participants gave high scores on a given plot on the visual analogue scale but ranked them low in the ranking preferences). This may show a lack of understanding of the movement report survey. Despite these limitations, the qualitative methods that are used during the study provided a more in-depth understanding of the participants' preferences of the metrics on the movement report. Moreover, we limited the number of visual plots we presented to participants to avoid exhausting them or biasing their interpretation of other plots. This limited our ability to test more complex plots that could be useful to clinicians. It should

also be noted that the feedback preferences identified by stroke survivors may not directly translate to improved motor performance in daily activities, as we did not provide real-time feedback to our participants. Moreover, our study design only allowed us to test terminal feedback in the form of knowledge of results. In future studies, stance percent should be averaged over longer time intervals and samples from short bouts of steps should be excluded from the averages.

Conclusions

Using the movement report as a starting place, we identified that stroke survivors found sensor-derived metrics intuitive and encouraging to incorporate their paretic arm/hand into daily activities and increase walking behavior (amount and symmetry). Our findings underscore the potential of using wearable sensors along with personalized goals to motivate engagement outside the clinical environment. Wearable technology could be introduced earlier in the rehabilitation process as a complement to clinical care, as therapist-patient interaction is crucial to foster accountability and motivation from the beginning. This work will establish the groundwork for the development of a robust personalized intervention strategy that leverages technology in the unsupervised setting to foster lasting behavior change in stroke survivors. Future work should assess whether feedback provided directly on the activity watch, by email or a companion application is effective for maximizing functional movement behavior.

Supplementary Information

The online version contains supplementary material available at <https://doi.org/10.1186/s12984-023-01271-z>.

Additional file 1: Interview guide.

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Author contributions

MD: conception and design, collection of data, analysis and interpretation of data, manuscript preparation-writing; AC: collection of data, analysis and interpretation of data, manuscript preparation-reviewing and editing; LB: conception and design, collection of data, manuscript preparation-reviewing and editing; TG: analysis and interpretation of data, manuscript-writing; JBR: conception and design, technology development, technical support, analysis and interpretation of data, manuscript preparation-reviewing and editing; DKZ: conception and design, technology development, analysis and interpretation of data, manuscript preparation-reviewing and editing; CJW: conception and design, supervision, analysis and interpretation of data, manuscript preparation-reviewing and editing. All authors read and approved the final manuscript.

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Availability of data and materials

The datasets used and/or analysed during the current study are available from the corresponding author on reasonable request.

Declarations

Ethics approval and consent to participate

All participants were fully informed of the procedures involved and provided informed consent. The study complies with standards of the Declaration of Helsinki. Study procedures were approved by the Institutional Review Board at the University of Southern California (HS 19-00984 and HS 20-00015).

Consent for publication

Not applicable.

Competing interests

CJW is a member of the data safety and monitoring board for Enspire DBS Therapy, Inc (DBS is Deep Brain Stimulation) and Brain Q (Syntactx); she receives an honorarium for her services. She is a member of the external advisory board for MicroTransponder, Inc., MedRhythm, Inc., and Axem Neurotechnology, Inc.; she receives payment for her consulting. She is an Editor of the 6th edition of Motor Control and Learning, published by Human Kinetics, Inc and receives royalty payments. She is an Editor for the 2nd Edition of Stroke Recovery and Rehabilitation, published by DemosMedical Publishers and receives royalty payments. JBR is a full-time employee of Flint Rehabilitation Devices, LLC. DKZ is a full-time employee and co-owner of Flint Rehabilitation Devices, LLC.

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