CORRECTION Open Access



Correction to: Soft robotic exosuit augmented high intensity gait training on stroke survivors: a pilot study

Sung Yul Shin^{1,2}, Kristen Hohl¹, Matt Giffhorn¹, Louis N. Awad^{3,5}, Conor J. Walsh^{4,5} and Arun Jayaraman^{1,2*}

Correction to:Journal of NeuroEngineering and Rehabilitation (2022) 19:51

https://doi.org/10.1186/s12984-022-01034-2

Following the publication of the original article [1], the text "Patents describing the exosuit components documented in this article have been filed with the U.S. Patent Office. They are licensed by ReWalk Robotics and C.J.W. is an inventor. CJW is a paid consultant for ReWalk Robotics" has been included under the Competing interests.

The original article has been corrected.

Author details

¹Max Nader Lab for Rehabilitation Technologies and Outcomes Research, Shirley Ryan AbilityLab, 355 E Erie St., Chicago, IL 60611, USA. ²Department of Physical Medicine and Rehabilitation, Northwestern University, 710 N Lake Shore Dr., Chicago, IL 60611, USA. ³College of Health and Rehabilitation Sciences: Sargent College, Boston University, Boston, USA. ⁴Harvard John A. Paulson School of Engineering and Applied Sciences, Harvard University, Cambridge, USA. ⁵Wyss Institute for Biologically Inspired Engineering, Harvard University, Cambridge, USA.

Accepted: 13 September 2022 Published online: 19 September 2022

Reference

 Shin SY, Hohl K, Giffhorn M, Awad LN, Walsh CJ, Jayaraman A. Soft robotic exosuit augmented high intensity gait training on stroke survivors: a pilot study. J Neuroeng Rehabil. 2022;19:51. https://doi.org/10.1186/ s12984-022-01034-2.

Publisher's Note

Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

The original article can be found online at https://doi.org/10.1186/s12984-022-01034-2.

*Correspondence: a-jayaraman@northwestern.edu

¹ Max Nader Lab for Rehabilitation Technologies and Outcomes Research, Shirley Ryan AbilityLab, 355 E Erie St., Chicago, IL 60611, USA Full list of author information is available at the end of the article



© The Author(s) 2022. **Open Access** This article is licensed under a Creative Commons Attribution 4.0 International License, which permits use, sharing, adaptation, distribution and reproduction in any medium or format, as long as you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons licence, and indicate if changes were made. The images or other third partial in this article are included in the article's Creative Commons licence, unless indicated otherwise in a credit line to the material. If material is not included in the article's Creative Commons licence and your intended use is not permitted by statutory regulation or exceeds the permitted use, you will need to obtain permission directly from the copyright holder. To view a copy of this licence, visit http://creativecommons.org/licenses/by/4.0/. The Creative Commons Public Domain Dedication waiver (http://creativecommons.org/publicdomain/zero/1.0/) applies to the data made available in this article, unless otherwise stated in a credit line to the data.