CORRECTION

Correction to: Soft robotic exosuit augmented high intensity gait training on stroke survivors: a pilot study

Sung Yul Shin[1,2], Kristen Hohl[1], Matt Giffhorn[1], Louis N. Awad[3,5], Conor J. Walsh[4,5] and Arun Jayaraman[1,2*]

Correction to:Journal of NeuroEngineering and Rehabilitation (2022) 19:51
https://doi.org/10.1186/s12984-022-01034-2

Following the publication of the original article [1], the text "*Patents describing the exosuit components documented in this article have been filed with the U.S. Patent Office. They are licensed by ReWalk Robotics and C.J.W. is an inventor. CJW is a paid consultant for ReWalk Robotics*" has been included under the Competing interests.

The original article has been corrected.

Reference
1. Shin SY, Hohl K, Giffhorn M, Awad LN, Walsh CJ, Jayaraman A. Soft robotic exosuit augmented high intensity gait training on stroke survivors: a pilot study. J Neuroeng Rehabil. 2022;19:51. https://doi.org/10.1186/s12984-022-01034-2.

Publisher's Note
Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

Author details
[1]Max Nader Lab for Rehabilitation Technologies and Outcomes Research, Shirley Ryan AbilityLab, 355 E Erie St., Chicago, IL 60611, USA. [2]Department of Physical Medicine and Rehabilitation, Northwestern University, 710 N Lake Shore Dr., Chicago, IL 60611, USA. [3]College of Health and Rehabilitation Sciences: Sargent College, Boston University, Boston, USA. [4]Harvard John A. Paulson School of Engineering and Applied Sciences, Harvard University, Cambridge, USA. [5]Wyss Institute for Biologically Inspired Engineering, Harvard University, Cambridge, USA.

*Correspondence: a-jayaraman@northwestern.edu
[1] Max Nader Lab for Rehabilitation Technologies and Outcomes Research, Shirley Ryan AbilityLab, 355 E Erie St., Chicago, IL 60611, USA
Full list of author information is available at the end of the article