

Correction

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Correction: Error mapping controller: a closed loop neuroprosthesis controlled by artificial neural networks

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After the publication of this work [1], we noticed in figure 2 (see Figure 1) the signal indicated as the desired output to train NF was not correctly reported in the figure. The training signal is the result of the difference between PW_{act} and PW_{des} as it is explained in the text, and as it is shown in the new figure we are showing here.

We apologize for the inconvenience that this inaccuracy in the paper might have caused to the readers.

References

1. Pedrocchi A, Ferrante S, De Momi E, Ferrigno G: **Error mapping controller: a closed loop neuroprosthesis controlled by artificial neural networks.** *Journal of NeuroEngineering and Rehabilitation* 2006, 3:25.

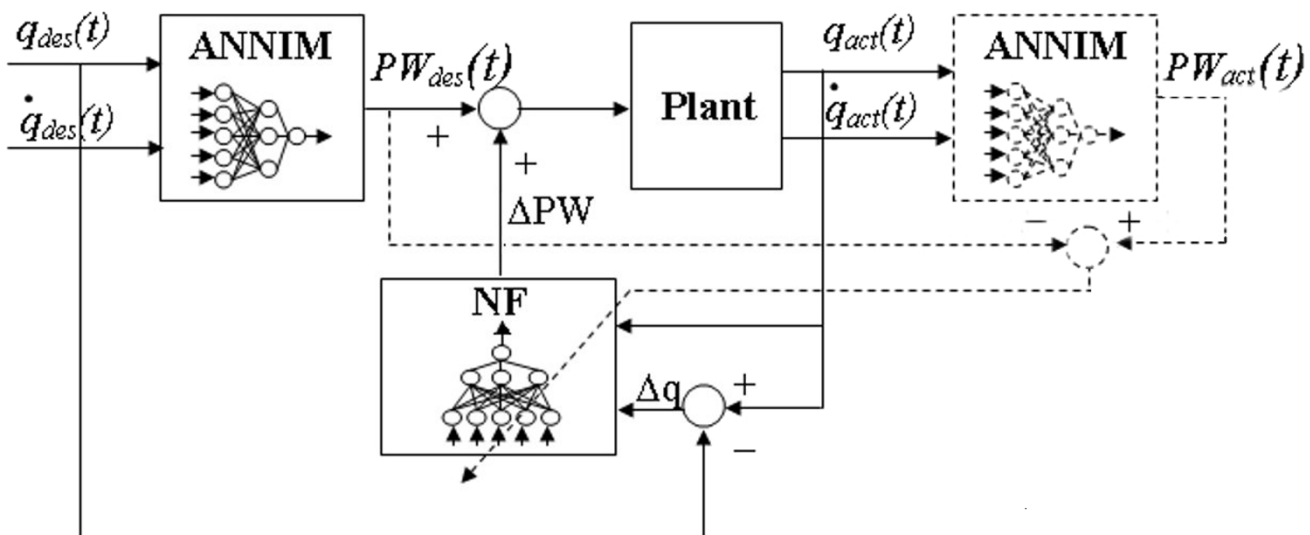


Figure 1

NF Training scheme. Scheme used to collect the training set of NF. The training output signal of NF is the difference between PW_{act} and PW_{des} and not the PW_{act} as it was wrongly indicated in figure 2 of the original paper.